Marine Propulsion Systems

ZF 45 A
8° Down angle, direct mount marine transmission.

**Description**
- Reverse reduction marine transmission with hydraulically actuated multi-disc clutches.
- Suitable for high performance applications in luxury motoryachts, sport fishers, express cruisers etc.
- Robust design also withstands continuous duty in workboat applications.
- Fully works tested, reliable and simple to install.
- Design, manufacture and quality control standards comply with ISO 9001.
- Compatible with all types of engines and propulsion systems, including waterjets and surface-piercing propellers, as applicable.

**Features**
- Lightweight and robust aluminum alloy casing (sea water resistant).
- Case hardened and precisely ground gear teeth for long life and smooth running.
- Output shaft thrust bearing designed to take maximum propeller thrust astern and ahead.
- B/W connection integrated with casing.
- Smooth and reliable hydraulic shifting with control lever for attachment of push-pull cable.
- Suitable for twin engine installations (same ratio and torque capacity in ahead or astern mode).
- Replaceable oil filter cartridge.
- Compact, space saving design due to 8° down-angle and beveloid gear principle.
- "SUPERSHIFT" clutch control.

**Options**
- Engine-matched dual stage coupling.
- SAE 3 and SAE 4 bell housings.
- Oil cooler complete with fittings and flexible oil hoses.
- Mounting brackets.
- Propeller shaft flange.
- Control cable bracket for mounting of push-pull cable to the control lever.
- Classification by all major Classification Societies on request.
- SAE «A» Power Take Off.
- Thermostatic valve for better performance of trolling valve in cold sea water.
- Trolling valve (mechanical) for slow-speed drive.
- Electric Trolling.
- Supershift (with Autotroll and Easidock).
## Pleasure Duty

### Ratings

<table>
<thead>
<tr>
<th>RATIOS</th>
<th>MAX. TORQUE</th>
<th>POWER/RPM</th>
<th>INPUT POWER CAPACITY</th>
<th>MAX. RPM</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>'A' Pos</td>
<td>'B' Pos</td>
<td>Nm</td>
<td>ftlb</td>
</tr>
<tr>
<td></td>
<td>2800 rpm</td>
<td>3300 rpm</td>
<td>3800 rpm</td>
<td></td>
</tr>
<tr>
<td>'A' POS = continuous running position (normally AHEAD). 'B' POS = reverse position.</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- 1.256 | 1.256 | 450 | 332 | 0.0471 | 0.0632 | 132 | 177 | 155 | 209 | 179 | 240 | 5500 |
- 1.514 | 1.514 | 450 | 332 | 0.0471 | 0.0632 | 132 | 177 | 155 | 209 | 179 | 240 | 5500 |
- 2.034 | 2.034 | 450 | 332 | 0.0471 | 0.0632 | 132 | 177 | 155 | 209 | 179 | 240 | 5500 |
- 2.435 | 2.435 | 420 | 310 | 0.0440 | 0.0590 | 123 | 165 | 145 | 195 | 167 | 224 | 5500 |

Last Updated: 12:28 PM GMT - 15-Dec-11
# Pleasure Duty Gasoline

<table>
<thead>
<tr>
<th>RATIOS</th>
<th>MAX. TORQUE</th>
<th>POWER/RPM</th>
<th>INPUT POWER CAPACITY</th>
<th>MAX. RPM</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>'A' Pos</td>
<td>'B' Pos</td>
<td>Nm</td>
<td>ftlb</td>
</tr>
<tr>
<td></td>
<td>1.256</td>
<td>1.256</td>
<td>450</td>
<td>332</td>
</tr>
<tr>
<td></td>
<td>1.514</td>
<td>1.514</td>
<td>450</td>
<td>332</td>
</tr>
<tr>
<td></td>
<td>2.034</td>
<td>2.034</td>
<td>450</td>
<td>332</td>
</tr>
<tr>
<td></td>
<td>2.435</td>
<td>2.435</td>
<td>420</td>
<td>310</td>
</tr>
</tbody>
</table>

*A POS = continuous running position (normally AHEAD).  B POS = reverse position.

Last Updated: 12:28 PM GMT - 15-Dec-11
### Light Duty

<table>
<thead>
<tr>
<th>RATIOS</th>
<th>MAX. TORQUE</th>
<th>POWER/RPM</th>
<th>INPUT POWER CAPACITY</th>
<th>MAX. RPM</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>'A' Pos</td>
<td>'B' Pos</td>
<td>Nm</td>
<td>ftlb</td>
</tr>
<tr>
<td></td>
<td>2100 rpm</td>
<td>2500 rpm</td>
<td>2800 rpm</td>
<td></td>
</tr>
<tr>
<td>1.256</td>
<td>1.256</td>
<td>430</td>
<td>317</td>
<td>0.0450</td>
</tr>
<tr>
<td>1.514</td>
<td>1.514</td>
<td>430</td>
<td>317</td>
<td>0.0450</td>
</tr>
<tr>
<td>2.034</td>
<td>2.034</td>
<td>430</td>
<td>317</td>
<td>0.0450</td>
</tr>
<tr>
<td>2.435</td>
<td>2.435</td>
<td>399</td>
<td>294</td>
<td>0.0418</td>
</tr>
</tbody>
</table>

*A' POS = continuous running position (normally AHEAD). *B' POS = reverse position.

---

**Diagram:**
- Top graph: KW vs. RPM
- Bottom graph: SAE HP vs. RPM

*Last Updated: 12:28 PM GMT - 15-Dec-11*
## Medium Duty

<table>
<thead>
<tr>
<th>RATIOS</th>
<th>MAX. TORQUE</th>
<th>POWER/RPM</th>
<th>INPUT POWER CAPACITY</th>
<th>MAX. RPM</th>
</tr>
</thead>
<tbody>
<tr>
<td>'A' Pos</td>
<td>'B' Pos</td>
<td>Nm</td>
<td>ftlb</td>
<td>kW</td>
</tr>
<tr>
<td>2100 rpm</td>
<td>2500 rpm</td>
<td>2800 rpm</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1.256</td>
<td>1.256</td>
<td>365</td>
<td>269</td>
<td>0.0382</td>
</tr>
<tr>
<td>1.514</td>
<td>1.514</td>
<td>365</td>
<td>269</td>
<td>0.0382</td>
</tr>
<tr>
<td>2.034</td>
<td>2.034</td>
<td>365</td>
<td>269</td>
<td>0.0382</td>
</tr>
<tr>
<td>2.435</td>
<td>2.435</td>
<td>341</td>
<td>252</td>
<td>0.0357</td>
</tr>
</tbody>
</table>

*A' POS = continuous running position (normally AHEAD).  'B' POS = reverse position.*

---

Last Updated: 12:28 PM GMT - 15-Dec-11
### Continuous Duty

<table>
<thead>
<tr>
<th>RATIOS</th>
<th>MAX. TORQUE</th>
<th>POWER/RPM</th>
<th>INPUT POWER CAPACITY</th>
<th>MAX. RPM</th>
</tr>
</thead>
<tbody>
<tr>
<td>'A' Pos &amp; 'B' Pos</td>
<td>Nm</td>
<td>ftlb</td>
<td>kW</td>
<td>hp</td>
</tr>
<tr>
<td></td>
<td>1800 rpm</td>
<td>2100 rpm</td>
<td>2400 rpm</td>
<td></td>
</tr>
<tr>
<td>1.256 &amp; 1.256</td>
<td>298</td>
<td>220</td>
<td>0.0312</td>
<td>0.0418</td>
</tr>
<tr>
<td>1.514 &amp; 1.514</td>
<td>298</td>
<td>220</td>
<td>0.0312</td>
<td>0.0418</td>
</tr>
<tr>
<td>2.034 &amp; 2.034</td>
<td>298</td>
<td>220</td>
<td>0.0312</td>
<td>0.0418</td>
</tr>
<tr>
<td>2.435 &amp; 2.435</td>
<td>274</td>
<td>202</td>
<td>0.0287</td>
<td>0.0385</td>
</tr>
</tbody>
</table>

* 'A' POS = continuous running position (normally AHEAD). 'B' POS = reverse position.

---

**Diagram:**

- **Graph 1:** Linear relationship between RPM and KW.
- **Graph 2:** Linear relationship between RPM and SAE-HP.

Last Updated: 12:28 PM GMT - 15-Dec-11
### SAE Bell Housing Dimensions

<table>
<thead>
<tr>
<th>SAE No.</th>
<th>A (mm)</th>
<th>B (mm)</th>
<th>C (mm)</th>
<th>Bolt Holes Diameter (mm)</th>
<th>No.</th>
<th>A (in)</th>
<th>B (in)</th>
<th>C (in)</th>
<th>D (in)</th>
<th>E (in)</th>
</tr>
</thead>
<tbody>
<tr>
<td>3</td>
<td>409.58</td>
<td>16.125</td>
<td>428.63</td>
<td>16.875</td>
<td>17.75</td>
<td>12</td>
<td>10.32</td>
<td>13/32</td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>361.95</td>
<td>14.25</td>
<td>381.0</td>
<td>15.0</td>
<td>15.875</td>
<td>12</td>
<td>10.32</td>
<td>13/32</td>
<td></td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>314.33</td>
<td>12.375</td>
<td>333.38</td>
<td>13.125</td>
<td>355.6</td>
<td>14</td>
<td>10.32</td>
<td>13/32</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Output Coupling Dimensions

<table>
<thead>
<tr>
<th>A (mm)</th>
<th>B (mm)</th>
<th>C (mm)</th>
<th>D (mm)</th>
<th>Bolt Holes Diameter (E)</th>
</tr>
</thead>
<tbody>
<tr>
<td>127</td>
<td>5.00</td>
<td>4.25</td>
<td>63.5</td>
<td>11.5</td>
</tr>
</tbody>
</table>

Output flange dimensions for Ratio 1.25 are different. See installation drawing for details.
Duty Definitions

PLEASURE DUTY DEFINITION
Highly intermittent operation with very large variations in engine speed and power
Average engine operating hours limit:
- 500 hours/year
- 300 hours/year for mechanical gearboxes
Typical hull forms: Planing.
Typical applications: Private, non-commercial, non-charter sport/leisure activities.

LIGHT DUTY DEFINITION
Intermittent operation with large variations in engine speed and power
Average engine operating hours limit:
- 2500 hours/year (for hydraulic gearboxes smaller than the ZF 650 series, 2000 hours/year).
Typical hull forms: Planing and semi-displacement.
Typical applications: Private and charter, sport/leisure activities, naval and police activities.

MEDIUM DUTY DEFINITION
Intermittent operation with some variations in engine speed and power
Average engine operating hours limit:
- 4000 hours/year.
- 3500 hours/year for gearboxes smaller than ZF 2000 series and workboat ZF W2700 series.
Typical hull forms: Semi-displacement and displacement.
Typical applications: Charter and commercial craft (example: crew boats and fast ferries), and naval and police activities.

CONTINUOUS DUTY DEFINITION
Continuous operation with little or no variations in engine speed and power
Average engine operating hours limit:
- Unlimited
Typical hull forms: Displacement.
Typical applications: Heavy duty commercial vessels, tugs, fishing boats.

Duty Ratings
Ratings apply to marine diesel engines at the indicated speeds. At other engine speeds, the respective power capacity (kW) of the transmission can be obtained by multiplying the Power/Speed ratio by the speed.

Approximate conversion factors:
- 1 kW = 1.36 metric hp
- 1 kW = 1.34 U.S. hp (SAE)
- 1 U.S. hp = 1.014 metric hp
- 1 Nm = 0.74 lb.ft.

Ratings apply to right hand turning engines, i.e. engines having counterclockwise rotating flywheels when viewing the flywheel end of the engine. These ratings allow full power through forward and reverse gear trains, unless otherwise stated.

Contact your nearest ZF Sales and Service office for ratings applicable to gas turbines, gasoline (petrol) engines, as well as left hand turning engines, and marine transmissions for large horsepower capacity engines.

Ratings apply to marine transmissions currently in production or in development and are subject to change without prior notice.

NOTE: THE MAXIMUM RATED INPUT POWER MUST NOT BE EXCEEDED (SEE RESPECTIVE RATINGS IN THE TECHNICAL DATA SHEETS)

Safe Operating Notice
The safe operation of ZF products depends upon adherence to technical data presented in our brochures. Safe operation also depends upon proper installation, operation and routine maintenance and inspection under prevailing conditions and recommendations set forth by ZF. Damage to transmission caused by repeated or continuous emergency manoeuvres or abnormal operation is not covered under warranty. It is the responsibility of users and not ZF to provide and install guards and safety devices, which may be required by recognized safety standards of the respective country (e.g. for U.S.A. the Occupational Safety Act of 1970 and its subsequent provisions).

Monitoring Notice
The safe operation of ZF products depends upon adherence to ZF monitoring recommendations presented in our operating manuals, etc. It is the responsibility of users and not ZF to provide and install monitoring devices and safety interlock systems as may be deemed prudent by ZF. Consult ZF for details and recommendations.

Torsional Responsibility and Torsional Couplings
The responsibility for ensuring torsional compatibility rests with the assembler of the drive and driven equipment. ZF can accept no liability for gearbox noise caused by vibrations or for damage to the gearbox, the flexible coupling or to other parts of the drive unit caused by this kind of vibration.

Contact ZF for further information and assistance. ZF recommends the use of a torsional limit stop for single engine powered boats, wherein loss of propulsion power can result in loss of control. It is the buyer's responsibility to specify this option, which can result in additional cost and a possible increase in installation length.

ZF can accept no liability for personal injury, loss of life, or damage or loss of property due to the failure of the buyer to specify a torsional limit stop. ZF selects torsional couplings on the basis of nominal input torque ratings and commonly accepted rated engine governed speeds. Consult ZF for details regarding speed limits of standard offering torsional couplings, which can be less than the transmission limit. Special torsional couplings may be required for Survey Society Ice Classification requirements.